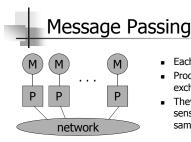


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- - Processes communicate by exchanging messages

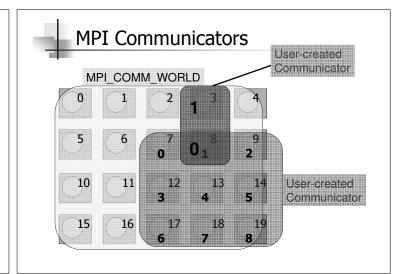
■ Each processor runs a process

- They cannot share memory in the sense that they cannot address the same memory cells
- The above is a programming model and things may look different in the actual implementation (e.g., MPI over Shared Memory)
- Message Passing is popular because it is general:
 - Pretty much any distributed system works by exchanging messages, at some level
 - Distributed- or shared-memory multiprocessors, networks of workstations, uniprocessors
- It is not popular because it is easy (it's not)



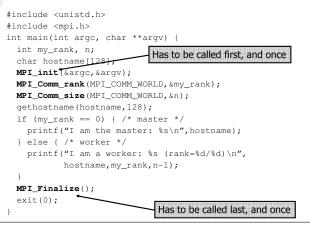
MPI Concepts

- Fixed number of processors
 - When launching the application one must specify the number of processors to use, which remains unchanged throughout execution
- Communicator
 - Abstraction for a group of processes that can communicate
 - A process can belong to multiple communicators
 - Makes is easy to partition/organize the application in multiple layers of communicating processes
 - Default and global communicator: MPI_COMM_WORLD
- Process Rank
 - The index of a process within a communicator
 - Typically user maps his/her own virtual topology on top of just linear ranks
 - ring, grid, etc.





A First MPI Program





Compiling/Running it

- Link with libmpi.a
- Run with mpirun
 - % mpirun -np 4 my_program <args>
 - requests 4 processors for running my_program with command-line arguments
 - see the mpirun man page for more information
 - in particular the -machinefile option that is used to run on a network of workstations
- Some systems just run all programs as MPI programs and no explicit call to ${\tt mpirun}$ is actually needed
- Previous example program:
- % mpirun -np 3 -machinefile hosts my_program I am the master: somehost1I am a worker: somehost2 (rank=2/2) I am a worker: somehost3 (rank=1/2)

(stdout/stderr redirected o the process calling moirun)



Point-to-Point Communication



- Data to be communicated is described by three things:
 - address
 - data type of the message
 - length of the message
- Involved processes are described by two things
 - communicator
 - rank
- Message is identified by a "tag" (integer) that can be chosen by the user



Point-to-Point Communication

- Two modes of communication:
 - Synchronous: Communication does not complete until the message has been received
 - Asynchronous: Completes as soon as the message is "on its way", and hopefully it gets to destination
- MPI provides four versions
 - synchronous, buffered, standard, ready



Synchronous/Buffered sending in MPI

- Synchronous with MPI Ssend
 - The send completes only once the receive has succeeded
 - copy data to the network, wait for an ack
 - The sender has to wait for a receive to be posted
 - No buffering of data
- Buffered with MPI Bsend
 - The send completes once the message has been buffered internally by MPI
 - Buffering incurs an extra memory copy
 - Doe not require a matching receive to be posted
 - May cause buffer overflow if many bsends and no matching receives have been posted yet



Standard/Ready Send

- Standard with MPI_Send
 - Up to MPI to decide whether to do synchronous or buffered, for performance reasons
 - The rationale is that a correct MPI program should not rely on buffering to ensure correct semantics
- Ready with MPI_Rsend
 - May be started only if the matching receive has been posted
 - Can be done efficiently on some systems as no handshaking is required



Example: Sending and Receiving

```
#include <unistd.h>
#include <mpi.h>
int main(int argc, char **argv) {
  int i, my_rank, nprocs, x[4];
  MPI_Init(&argc,&argv);
  MPI_Comm_rank(MPI_COMM_WORLD,&my_rank);
                                              destination
  if (my_rank == 0) { /* master *}
    x[0]=42; x[1]=43; x[2]=44; x[3]=45
                                                source
    MPI_Comm_size(MPI_COMM_WORLD, &nprocs)
    for (i=1;i<nprocs;
      MPI_Send(x, 4, MPI_INT, 1
                                                user-defined
  } else { /* worker *.
                                                  tag
    MPI_Status status
    MPI_Redv x, 4, MP _INT, 0, 0, MPI_COMM_WORLD
                                                &status);
  MPI_Finalize()
                  elements to receive
                                        like MPI_Get_count(), etc
```



Non-blocking Communication

 MPI_Issend, MPI_Ibsend, MPI_Isend, MPI_Irsend, MPI_Irecv

```
MPI_Request request;
MPI_Isend(&x,1,MPI_INT,dest,tag,communicator,&request);
MPI_Irecv(&x,1,MPI_INT,src,tag,communicator,&request);
```

 Functions to check on completion: MPI_Wait, MPI_Test, MPI_Waitany, MPI_Testany, MPI_Waitall, MPI_Testall, MPI_Waitsome, MPI_Testsome.

```
MPI_Status status;
MPI_Wait(&request, &status) /* block */
MPI_Test(&request, &status) /* doesn't block */
```



Collective Communication

- Operations that allow more than 2 processes to communicate simultaneously
 - barrier
 - broadcast
 - reduce
- All these can be built using point-to-point communications, but typical MPI implementations have optimized them, and it's a good idea to use them
- In all of these, all processes place the same call (in good SPMD fashion), although depending on the process, some arguments may not be used



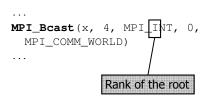
- Synchronization of the calling processes
 - the call blocks until all of the processes have placed the call
- No data is exchanged

...
MPI_Barrier(MPI_COMM_WORLD)
...



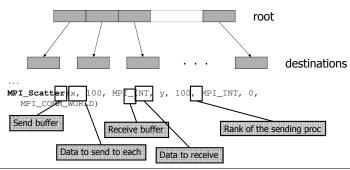
Broadcast

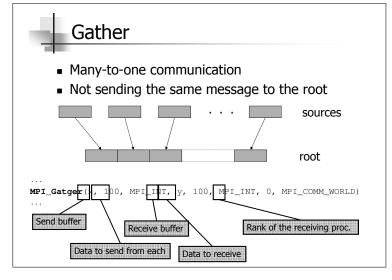
- One-to-many communication
- Note that multicast can be implemented via the use of communicators (i.e., to create processor groups)

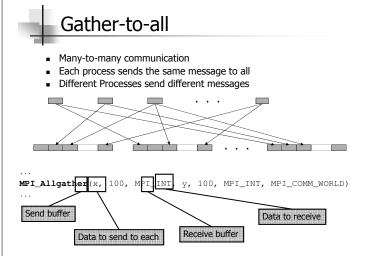


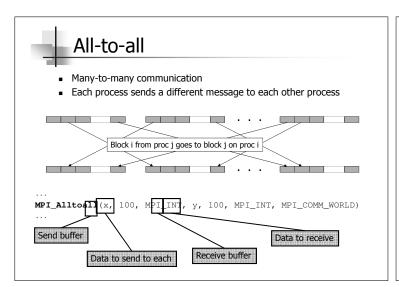


- One-to-many communication
- Not sending the same message to all











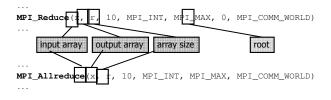
Reduction Operations

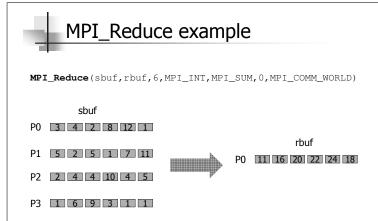
- Used to compute a result from data that is distributed among processors
 - often what a user wants to do anyway
 - so why not provide the functionality as a single API call rather than having people keep re-implementing the same things
- Predefined operations:
 - MPI_MAX, MPI_MIN, MPI_SUM, etc.
- Possibility to have user-defined operations



MPI_Reduce, MPI_Allreduce

- MPI_Reduce: result is sent out to the root
 - the operation is applied element-wise for each element of the input arrays on each processor
- MPI Allreduce: result is sent out to everyone

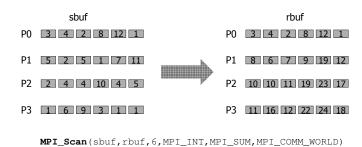






MPI_Scan: Prefix reduction

process i receives data reduced on process 0 to i.



4

User-defined reduce operations

MPI_Op_create(MPI_User_function
 *function,

int commute, MPI_Op *op)

- pointer to a function with a specific prototype
- commute (0 or 1) allows for optimization if true

typedef void MPI_User_function(void *a,
 void *b, int *len, MPI_Datatype
 *datatype);

■ b[i] = a[i] op b[i], for i=0,...,len-1



MPI_Op_create example

```
void myfunc(void *a, void *b, int *len, MPI_Datatype
              *dtype) {
                   int i;
                     for (i = 0; i < *len; ++i) ((int*)b)[i] =
              ((int*)b)[i] + ((int*)a)[i];
int main(int argc, char *argv[]) {
                    int myrank, nprocs, sendbuf, recvbuf;
                    MPI_Op myop;
                    MPI_Init(&argc, &argv);
                    MPI_Comm_size(MPI_COMM_WORLD, &nprocs);
                    MPI_Comm_rank(MPI_COMM_WORLD, &myrank);
                    \label{eq:MPI_Op_create(myfunc, 1, &myop);} \end{substitute} % \begin{substitute}(100,0) \put(0.0,0){\line(0,0){100}} \put(0.0,0){\
                     sendbuf = 2*myrank+1;
              numbers
                   MPI_Reduce(&sendbuf, &recvbuf, 1, MPI_INT, myop, 0,
             MPI_COMM_WORLD);
                     if(myrank == 0) printf("%d^2 = %d\n", nprocs,
```



More Advanced Messages

Regularly strided data



Blocks/Elements of a matrix

Data structure

```
struct {
    int a;
    double b;
}
```

A set of variables

```
int a; double b; int x[12];
```



Derived Data Types

- A data type is defined by a "type map"
 - set of <type, displacement> pairs
- Created at runtime in two phases
 - Construct the data type from existing types
 - Commit the data type before it can be used
- Simplest constructor: contiguous type



MPI_Type_contiguous example

```
int buffer[100];
MPI_Datatype chvec;
MPI_Type_contiguous(20, MPI_CHAR,
    &chvec);
MPI_Type_commit(&chvec);
...
MPI_Send(buffer,1,chvec,1,44,MPI_COMM_WOR
    LD);
MPI_Type_free(&chvec);
```



MPI_Type_indexed()

```
int MPI_Type_indexed(int count,
    int *array_of_blocklengths,
    int *array_of_displacements,
    MPI_Datatype oldtype,
    MPI_Datatype *newtype)
```



Len[1]

```
MPI_Type_indexed example
 int vector[4][3] = { 1, 12, 13, 21, 22, 23, 31, 32, 33,
                    ندل ۱۰
 int wvector[4][3]
 int blocklengths[2] = \{2, 2\};
 int displacements[2] = {4, 10}; int rank;
 MPI_Datatype mytype;
 MPI_Status mystatus;
 MPI_Init(&argc, &argv);
 MPI_Type_indexed(4, blocklengths, displacements, MPI_INT,
 MPI_Type_commit(&mytype);
 MPI_Comm_rank(MPI_COMM_WORLD, &rank);
 if (rank == 0) MPI_Send(vector, 1, mytype, 1, 0,
MPI_COMM_WORLD);
     MPI_Recv(wvector, 1, mytype, 0, 0, MPI_COMM_WORLD,
&mystatus);
       for (i = 0; i < 4; i++) { printf("\n");
              for (j=0; j < 3; j++) printf("%02d ",
```



MPI_Type_struct()

int MPI_Type_struct(int count,
 int *array_of_blocklengths,
 MPI_Aint *array_of_displacements,
 MPI_Datatype *array_of_types,
 MPI_Datatype *newtype)





MPI_Type_vector example

■ Sending the 5th column of a 2-D matrix:

double results[IMAX][JMAX];
MPI_Datatype newtype;
MPI_Type_vector (IMAX, 1, JMAX, MPI_DOUBLE, &newtype);
MPI_Type_Commit (&newtype);
MPI_Send(&(results[0][5]), 1, newtype, dest, tag, comm);



